

### MAIN FEATURES

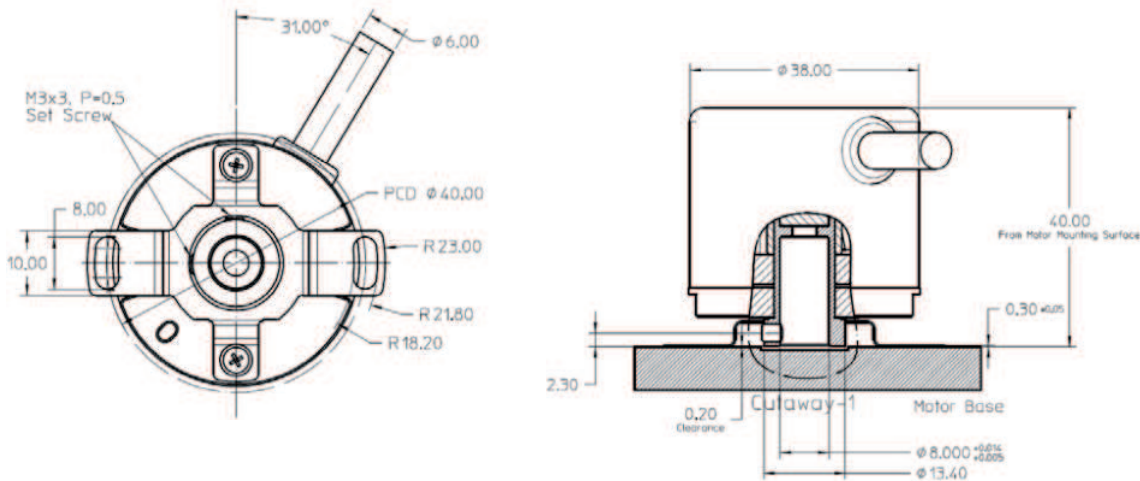
Miniaturized optical multiturn absolute encoder for high end application. Thanks to BiSS-C interface and high resolution it can be used in robotics, motor feedback and CNC machines.

- Optical sensor technology (OptoASIC + Energy Harvesting)
- 39 bit total resolution (23 bit single turn + 16 bit multiturn)
- Power supply +5 VDC with BiSS-C as electronic interface
- Cable output
- Blind hollow shaft diameter up to 8 mm
- Mounting by stator coupling
- Operating temperature -20° ... +105°C (-4° ... +221°F)

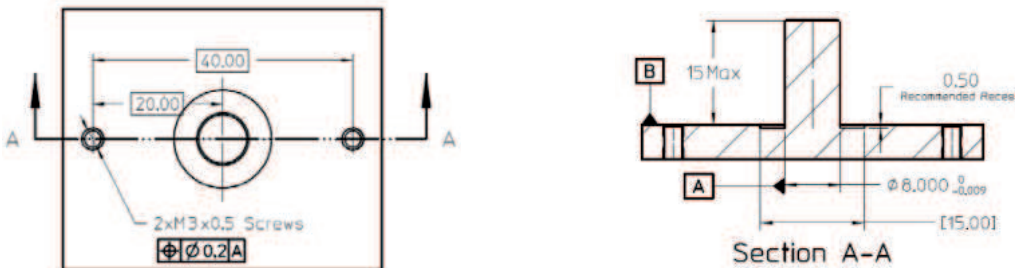


ORDERING CODE		AAM	38F	16	/	23	B	5	B	8	X	X	PR	.XXX
<b>SERIES</b>	absolute multiurn encoder	AAM												
<b>MODEL</b>	blind hollow shaft with stator coupling	38F												
<b>MULTITURN RESOLUTION</b>	bit	16												
<b>SINGLETURN RESOLUTION</b>	bit	23												
<b>CODE TYPE</b>	binary	B												
<b>POWER SUPPLY</b>	5 V DC	5												
<b>ELECTRONIC INTERFACE</b>	BiSS-C	B												
<b>BORE DIAMETER</b>	mm	6												
	(1/4") mm	6,35												
	mm	8												
<b>ENCLOSURE RATING</b>	IP 50	X												
<b>OPTIONS</b>	to be reported	X												
<b>OUTPUT TYPE</b>	radial cable (standard lenght 0,2m)	PR												
<b>VARIANT</b>	custom version	XXX												

AAM 38 F



RECOMMENDED SHAFT AND MOUNTING HOLES REQUIREMENT



dimensions in mm

ELECTRICAL SPECIFICATIONS	
Multiturn resolution	16 bit
Singleturn resolution	23 bit
Fault status	8 bit
CRC	8 bit
Power supply	4,75 ... 5,25 V DC
Current consumption without load	< 120 mA
Output type	BiSS-C (SN65LBC179Q)
Code type	binary
Clock frequency (MA)	80 kHz ... 10 MHz
Position Calculation Time	Refer to BiSS-C $T_{busy\ time}$
Accuracy	$\pm 80$ arc-sec
Counting direction	decreasing clockwise (shaft view)
Start-up time	500 ms
Electromagnetic compatibility	IEC 61000-6-2 IEC 61000-6-4

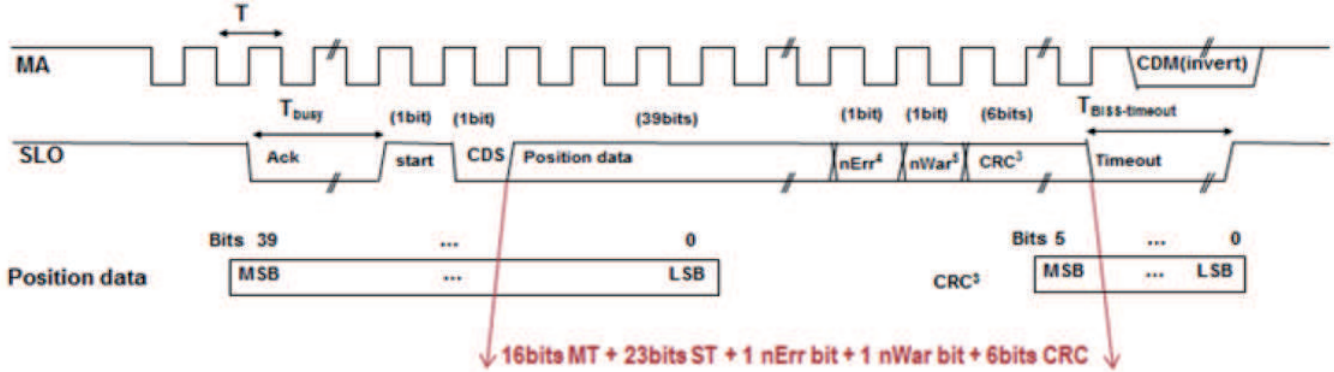
MECHANICAL SPECIFICATIONS	
Shaft diameter	$\varnothing 6 / 6,35$ (1/4") / 8 mm
Enclosure rating	IP 50 (IEC 60529)
Rotation speed	6000 rpm continuous
Shock	200 G, 6 ms (IEC 60068-2-27)
Vibration	10 G, 10 ... 2000 Hz (IEC 60068-2-6)
Shaft radial play allowed	$\pm 0,05$ mm
Shaft radial play allowed	$\pm 0,1$ mm
Shaft material	brass
Housing material	steel
Bearing stage material	aluminum
Bearings	2 ball bearings
Bearings life	$10^9$ revolutions
Operating temperature	-20° ... +105°C (-4° ... +221°F)
Storage temperature	-20° ... +105°C (-4° ... +221°F)
Fixing torque for shaft grains	1 Nm recommended
Fixing torque for spring screws	0,35 Nm recommended for M3 screws (not provided)
Weight	150 g (5,29 oz)

CONNECTIONS	
Function	Cable output
+ Vdc	red
Ground	black
serial data (SLO) +	orange
serial data (SLO) -	blue
serial clock (MA)+	brown
serial clock (MA) -	white

**BISS-C TIMING DIAGRAM**

Parameter	Symbol	Value			Unit	Note
		Min	Typical	Max		
MA frequency	$f_{MA}$	0,08	–	10	MHz	1
Busy	$T_{busy}$	$2 / f_{MA} + 3,35 \mu s$	–	$2,5 / f_{MA} + 3,75 \mu s$	$\mu s$	2
Timeout	$t_{Biss-timeout}$	$1,5 / f_{MA}$	–	$1,5 / f_{MA} + 90 ns$	ns	2

Figure 1 Timing Characteristics of MA and SLO



1. MA low-time =  $0,50 / f_{MA}$ ; high-time =  $0,50 / f_{MA}$
2. Refer to Figure 1 for timing description
3. CRC Polynomial = Invert of  $(X^6 + X^1 + X^0)$
4. nErr bit is active low. (Combine all the Error Status and reflect in nERR bit)
5. nWar bit is active low. (Combine all the Warning Status and reflect in nERR bit)

**Description**

Refer to BiSS-C Interface Protocol Description Rev C5 document for detailed information of BiSS-C Register Communication.  
[http://biss-interface.com/files/Bissinterface\\_c5es.pdf](http://biss-interface.com/files/Bissinterface_c5es.pdf)

Figure 2 Register write access

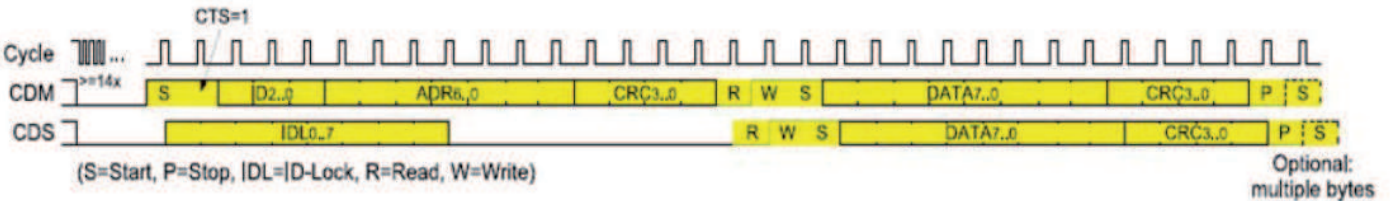


Figure 3 Register read access

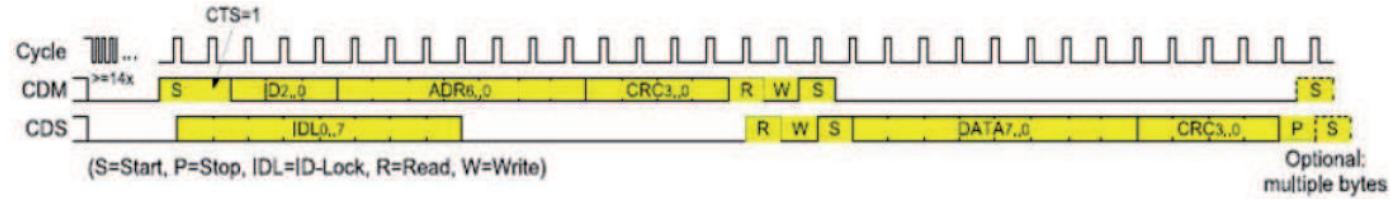


Figure 4 Writing several registers

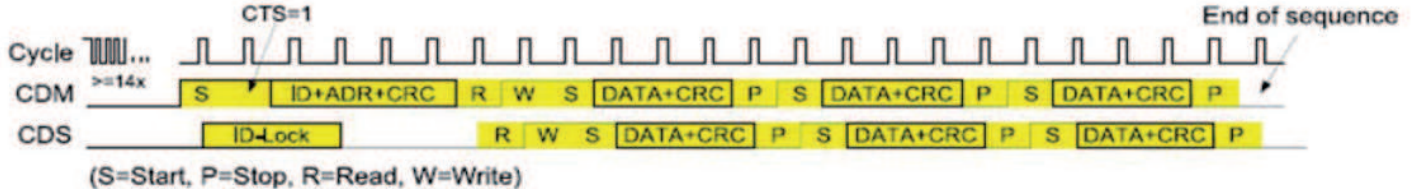
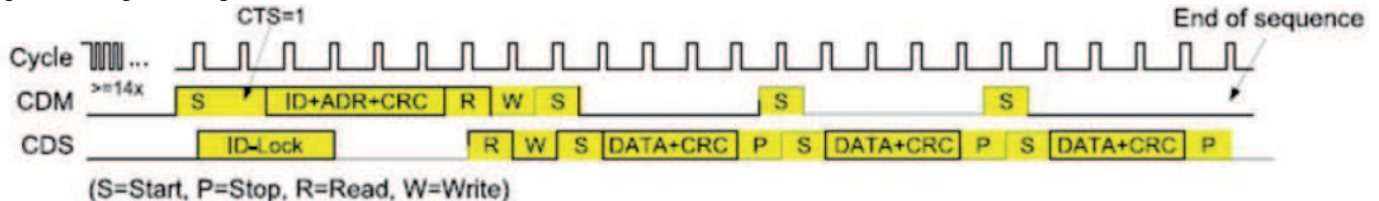


Figure 5 Reading several registers



Refer to BiSS-C Interface Protocol Description Rev C5 document for detail information of BiSS-C Register Assignment.

There are a total of 10 register banks user areas (register bank 0 to register bank 9) that are accessible by users.  
The memory data is kept in nonvolatile memory.

## REGISTER ASSIGNMENTS

Address (Decimal)	Address (Hexadecimal)	Name	Size	Memo
0 ... 63	0x00 ... 0x3F	Register bank	64 bytes	
64	0x40	Bank selection	0 ... 8 bits (1 byte)	a, b
65	0x41	EDS-Bank	0 ... 8 bits (1 byte)	a,c
66 ... 67	0x42 ... 0x43	Profile ID	16 bits (2 bytes)	c, d
68 ... 71	0x44 ... 0x47	Serial number	32 bits (4 byte)	c, d
72 ... 119	0x48 ... 0x77	Slave register	48 bytes	
120 ... 125	0x78 ... 0x7D	Device ID	48 bits (6 bytes)	c, d
126 ... 127	0x7E ... 0x7F	Manufacturer ID	16 bits (2 bytes)	c, d

a. If no blank switchover is used, the register should not be implemented

b. Unused register contents must therefore be filled with "0"

c. Register is protected against accidental writing

d. The value is saved as a big endian; i.e., with the highest value byte at the lowest value address

EEPROM Address	BiSS-C		Memo
	Page	Address	
000 ... 27Fh	0	00 ...3Fh	User area
	1	00 ...3Fh	
	2	00 ...3Fh	
	3	00 ...3Fh	
	4	00 ...3Fh	
	5	00 ...3Fh	
	6	00 ...3Fh	
	7	00 ...3Fh	
	8	00 ...3Fh	
280 ... 2FFh	9	00 ...3Fh	Reserved area
	10	00 ...3Fh	
300 ... 37Fh	11	00 ...3Fh	
	12	00 ...3Fh	
380 ... 3BFh	13	00 ...3Fh	
	14	00 ...3Fh	
3C0 ... 3FFh	-	40h	Bank selection
		41h	EDS-Bank (User prohibited write) – Not Available
		42 ... 43h	Profile ID (User prohibited write)
		44 ... 47h	Serial Number (User prohibited write)
		48 ... 77h	Slave Register (Refer to the Slave Register Description – user area)
		78 ... 7Dh	Device ID (User prohibited write)
		7E ... 7F	Manufacturer ID (User prohibited write)

## SLAVE REGISTER DESCRIPTION

## Address 72 (0x48) - Error status [7...0]

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
NA			MLSErr Error	Multi-turnErr Error	STErr Error	MemoryErr Error	XCErr Error

## Address 73 (0x49) - Warning status [7...0]

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
NA						Lis_Err Warning	LED_Err Warning

## Address 74 (0x4A) - Encoder Clear Command

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
NA				Warning clear command*	Error clear command*	ST clear command*	MT clear command*

\* Encoder Clear Command operation

- a. Write 1 to execute one time clear command
- b. Only one command should be accessed for each time